

Stochastic models of reaction networks

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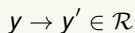
Pula, Italy

June 11, 2024

- 1 Introduction to the stochastic models.
- 2 Large volume limits (on compact time intervals)
- 3 Convergence to equilibrium for stochastic models, what does it mean and when does it happen?
- 4 Similarities and discrepancies between the behavior of the stochastic and deterministic models as $t \rightarrow \infty$.

We've seen reaction networks: $\{S, C, \mathcal{R}\}$

- S : species.
For example $\{A, B\}$.
- C : complexes, linear combinations of the species over \mathbb{Z} .
For example, $\{2A, A + B, \dots\}$
- \mathcal{R} : reactions. We will denote by



with usual convention (abuse of notation)

$$y' - y \in \mathbb{Z}^d.$$

For example, $\{2A \rightarrow A + B, \dots\}$

Will assume certain terminology: linkage class, weakly reversible, detailed balanced, complex balanced, stoichiometric compatibility class.

We know that for a given network $\{S, C, R\}$ we have a system of autonomous ODEs that govern dynamics of the concentrations

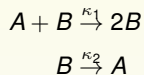
$$\dot{x}(t) = \sum_{y \rightarrow y' \in \mathcal{R}} \kappa_{y \rightarrow y'} x(t)^y (y' - y),$$

where for vectors u, v , we have

$$u^v = \prod_{i=1}^d u_i^{v_i}.$$

where we take $0^0 = 1$.

- Assuming **deterministic mass-action kinetics**.
- This model is appropriate when the **counts of the molecules are high**, which I'll discuss soon.



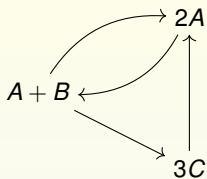
yields

$$\dot{X}_A(t) = -\kappa_1 X_A(t) X_B(t) + \kappa_2 X_B(t)$$

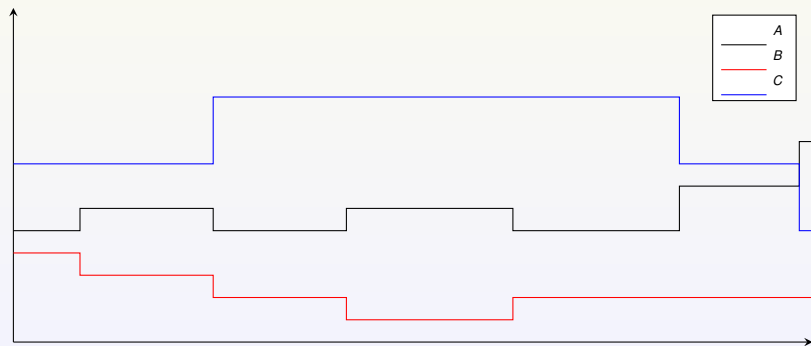
$$\dot{X}_B(t) = \kappa_1 X_A(t) X_B(t) - \kappa_2 X_B(t)$$

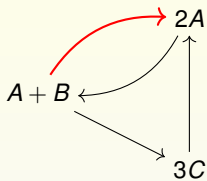
or

$$\dot{X}(t) = \kappa_1 X_A(t) X_B(t) \begin{pmatrix} -1 \\ 1 \end{pmatrix} + \kappa_2 X_B(t) \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

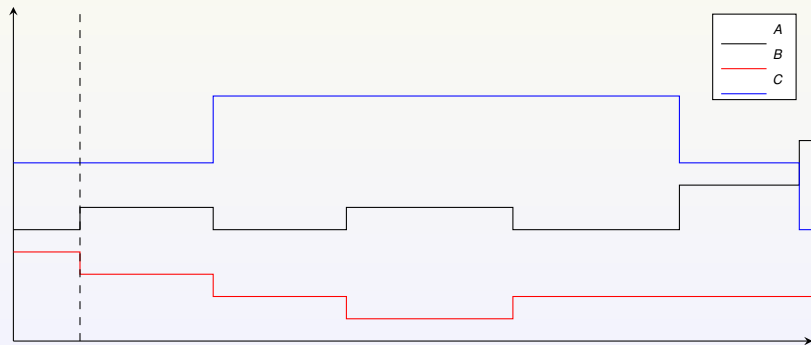


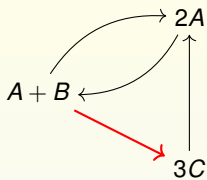
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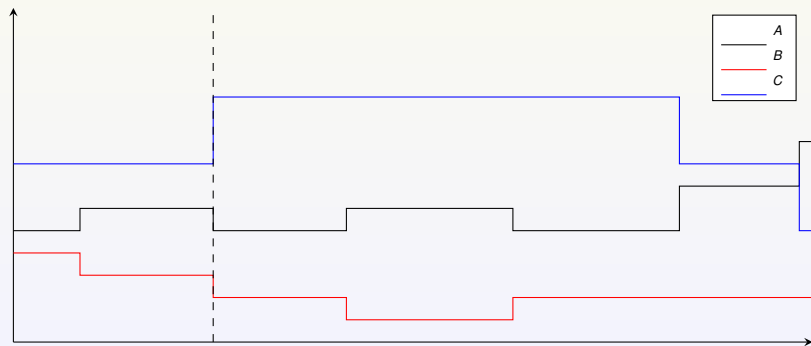


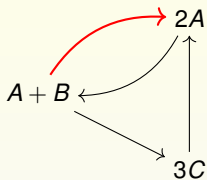
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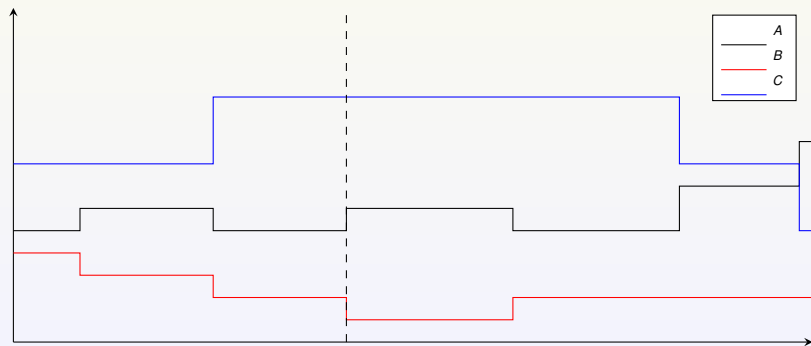


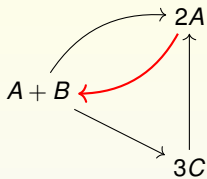
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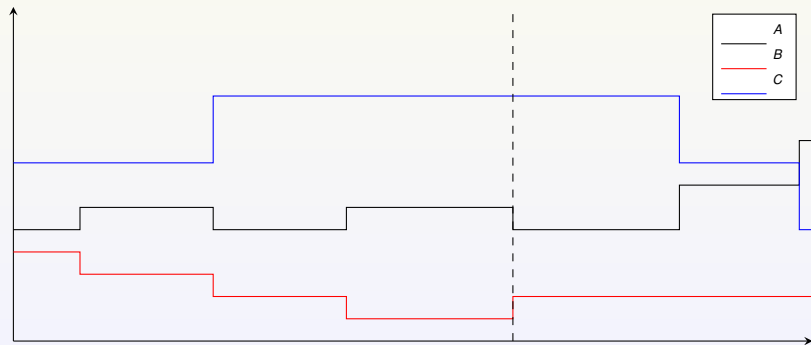


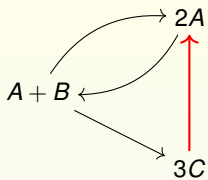
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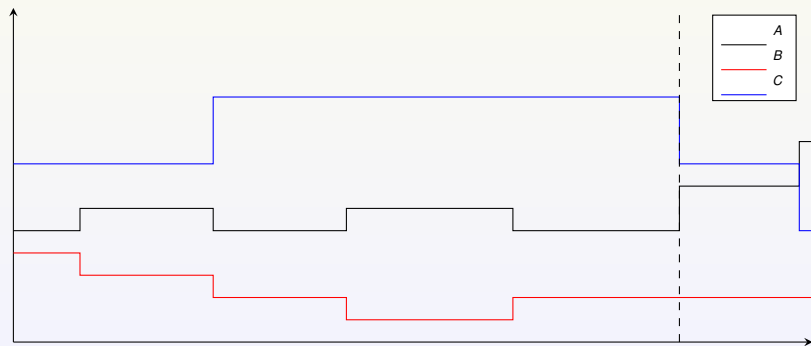


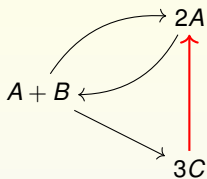
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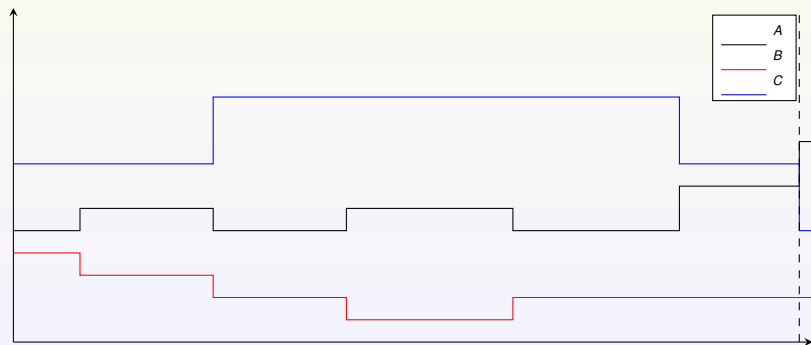


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The dynamics can be specified if we can answer the following two questions sequentially:

- 1 when will the next reaction take place?
- 2 which reaction will take place next?

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Modelling assumption:

- at time t , reaction $y \rightarrow y' \in \mathcal{R}$ has an associated clock set to go off after an amount of time given by an exponential random variable with a parameter of

$$\lambda_{y \rightarrow y'}(X(t)),$$

independently on what happened in the past. The higher the parameter, the lower tends to be the exponential random variable.

- when the first such clock goes off, the associated reaction takes place.
- Throw away all the clocks.
- Now repeat.

Stochastic model

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The described process is a [continuous-time Markov chain](#).

By the properties of exponential random variables, an equivalent simulation strategy is given by the [Gillespie's algorithm](#).

- Suppose $X(t) = x$.

- Let

$$\lambda_0(x) = \sum_{y \rightarrow y' \in \mathcal{R}} \lambda_{y \rightarrow y'}(x)$$

and let $\Delta = \text{Exp}(\lambda_0(x))$.

- Independently choose $\bar{y} \rightarrow \bar{y}' \in \mathcal{R}$ with probability

$$\frac{\lambda_{\bar{y} \rightarrow \bar{y}'}(x)}{\sum_{y \rightarrow y'} \lambda_{y \rightarrow y'}(x)}.$$

- Update $X(t + s) = X(t)$ for $0 \leq s < \Delta$ and

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This is not efficient if rates are very high, so many reactions take place in a short amount of time and use a lot of computational power.

Mass-action kinetics

A popular choice for intensity functions is **stochastic mass-action kinetics**:

$$\lambda_{y \rightarrow y'}(x) = \kappa_{y \rightarrow y'} \prod_i \frac{x_i!}{(x_i - y_i)!}.$$

Example: If $S_1 \rightarrow \text{anything}$, then

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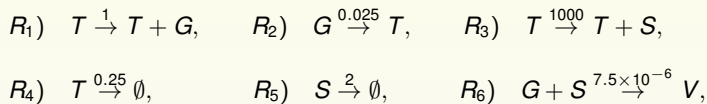
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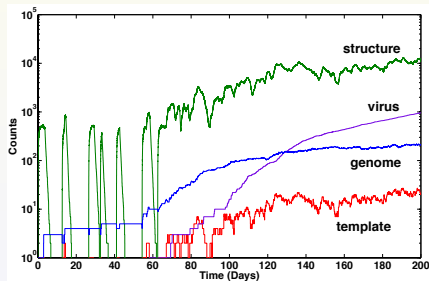
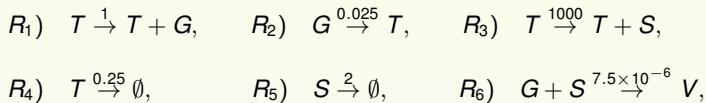
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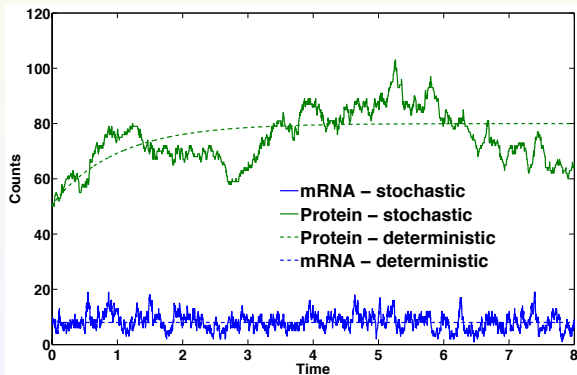
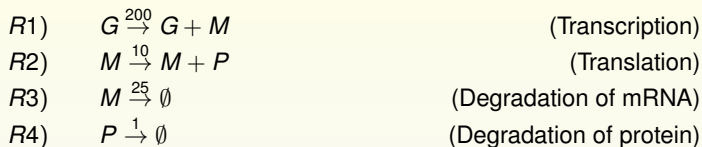
Example: If $2S_2 \rightarrow \text{anything}$, then

$$\lambda_{y \rightarrow y'}(x) = \kappa_{y \rightarrow y'} \frac{x_2!}{(x_2 - 2)!} = \kappa_{y \rightarrow y'} x_2(x_2 - 1).$$

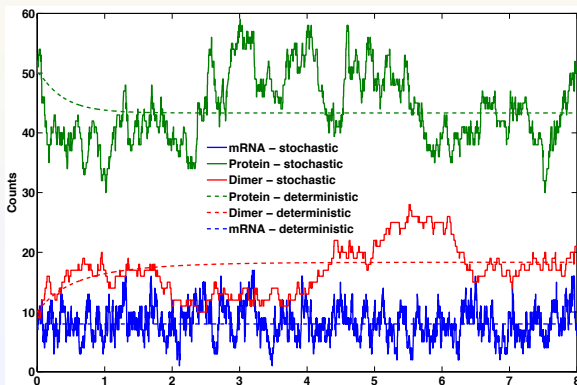
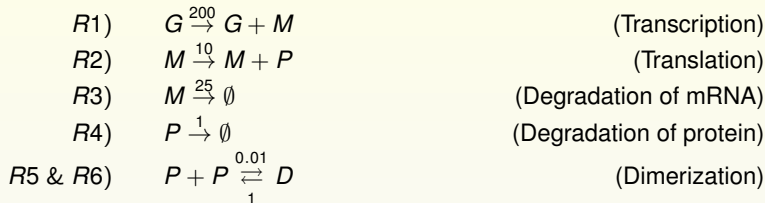
Nonlinear if any reaction requires two or more molecules.

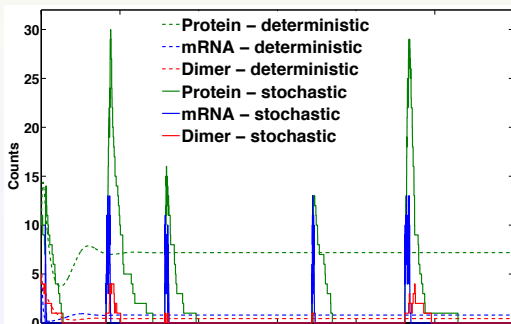
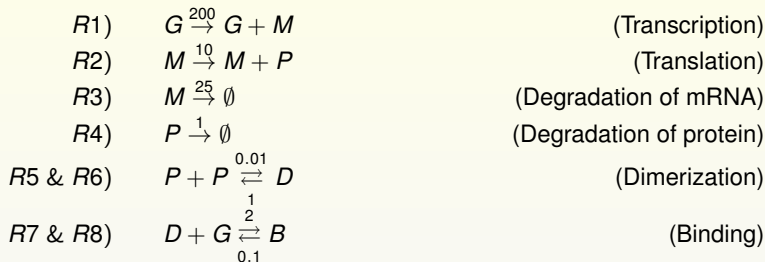






Gene network





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Two research directions stem from this:

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 - ...
- Use an approximate simulation strategy, such as tau leaping: count the number of reactions that would occur in a time window if the state were constant, then update.

Section 1

Structural differences between deterministic and stochastic reaction networks

If at time t^* the reaction $y \rightarrow y'$ takes place, then

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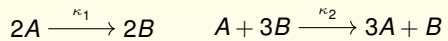
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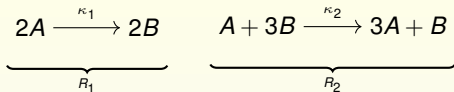
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The state space for X_t is $\mathbb{N}^{|S|}$.

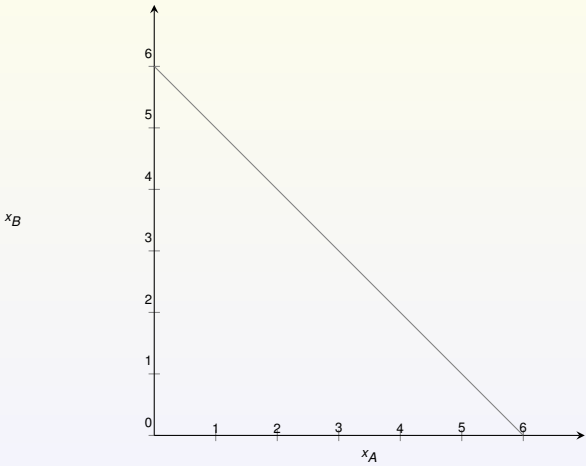
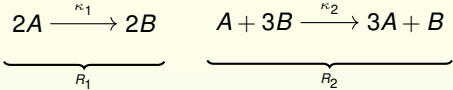
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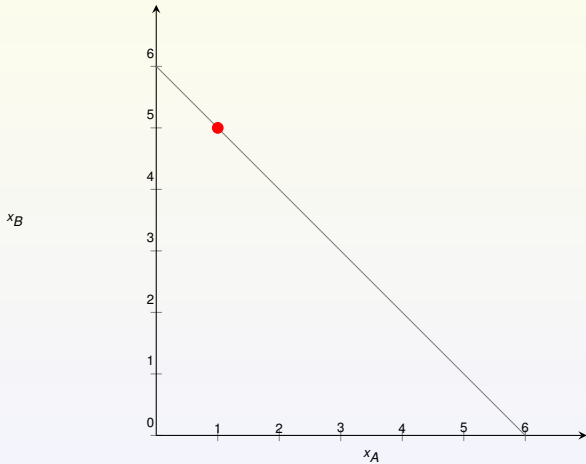
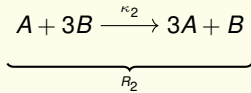
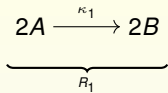
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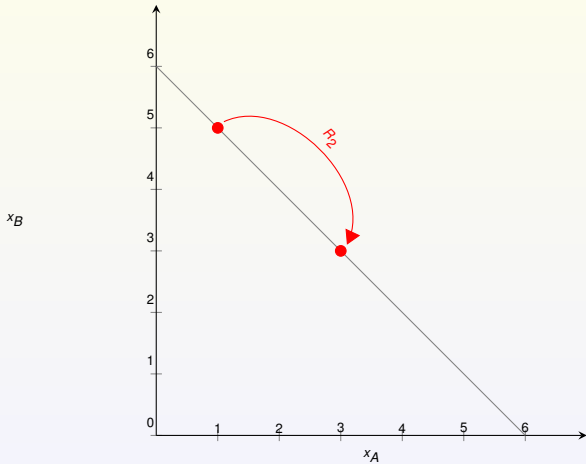
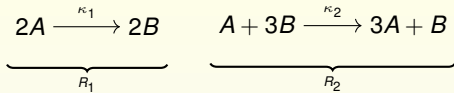
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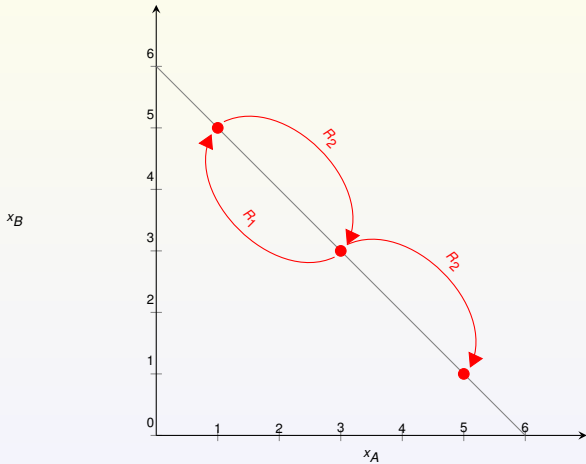
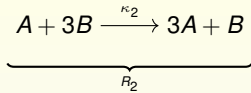
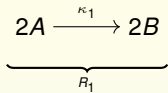
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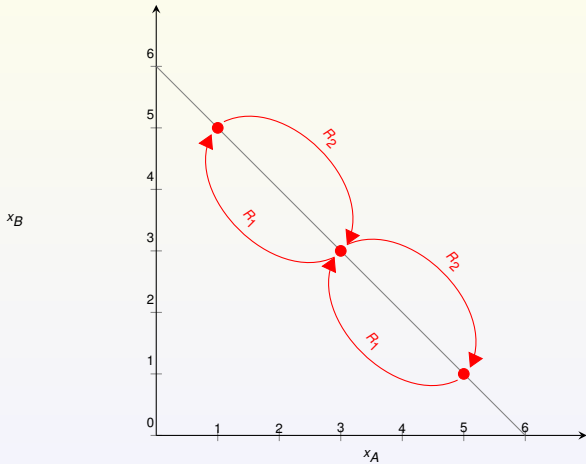
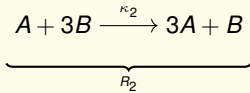
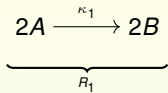
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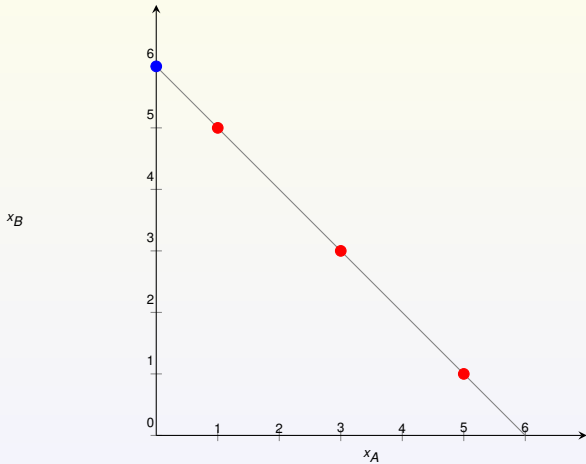
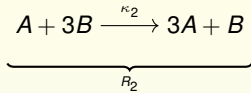
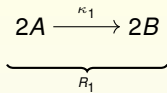
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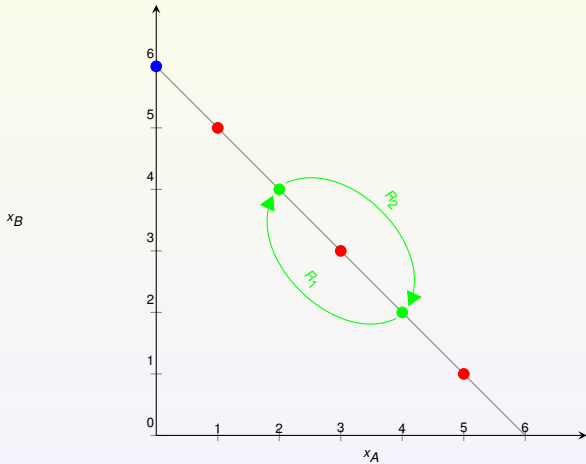
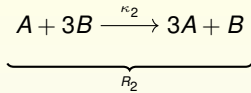
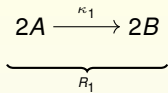
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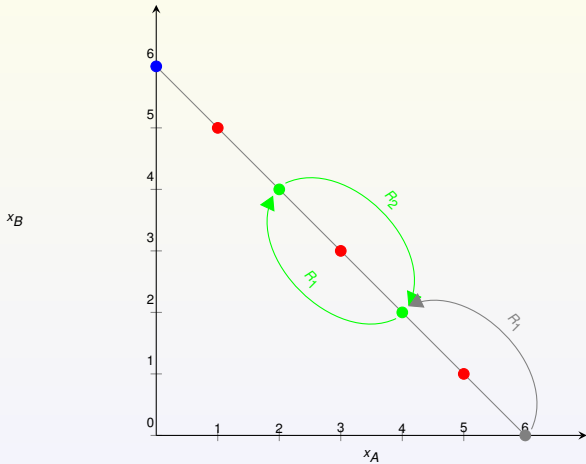
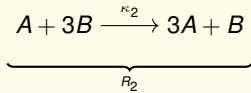
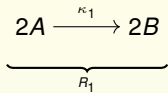
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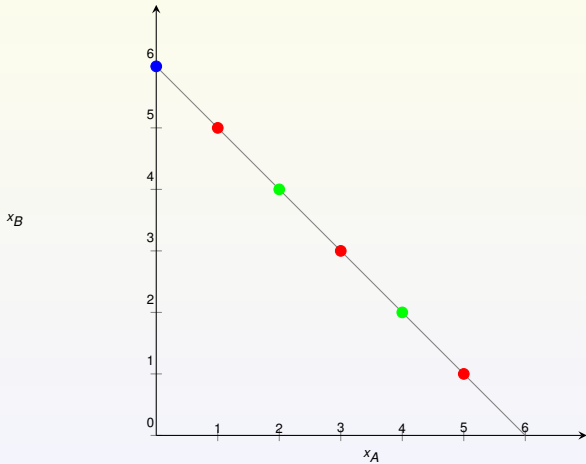
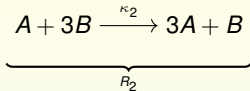
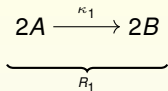
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Definition (Switched on/off reactions)

A reaction $y_r \rightarrow y_r'$ is **switched on** at x if $\lambda_r(x) > 0$, otherwise it is **switched off**.

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A reaction $y_r \rightarrow y'_r$ is **switched on** at x if $\lambda_r(x) > 0$, otherwise it is **switched off**.

Definition (Accessible states)

z is **accessible** from x if $\exists (y_i \rightarrow y'_i)_{i=1, \dots, q}$ such that

$$z = x + \sum_{i=1}^q \xi_i,$$

and for any $1 \leq j \leq q$, $y_j \rightarrow y'_j$ is switched on at $x + \sum_{i=1}^{j-1} \xi_i$. In particular, x is accessible from x .

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Definition (Communicating states)

x and z are **communicating** if z is accessible from x and vice versa.

Definition (Irreducible components)

An **irreducible components** of a reaction network is a set $\Gamma \subseteq \mathbb{N}^{|S|}$ such that, for any $x \in \Gamma$, $z \in \Gamma$ if and only if it is accessible from x .

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Γ is an irreducible component if and only if all the states of Γ are communicating, and no state outside Γ is accessible from any $x \in \Gamma$.

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Γ is an irreducible component if and only if all the states of Γ are communicating, and no state outside Γ is accessible from any $x \in \Gamma$.

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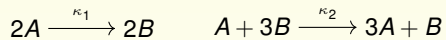
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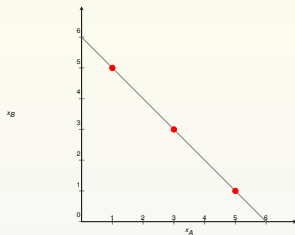
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- The irreducible components are not necessarily a partition of $\mathbb{N}^{|\mathcal{S}|}$;
- If a single state constitutes an irreducible component, it is a **absorbing state**.

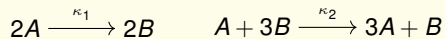
Consider



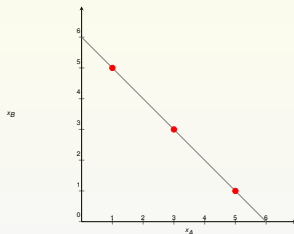
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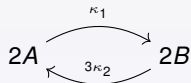
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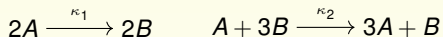
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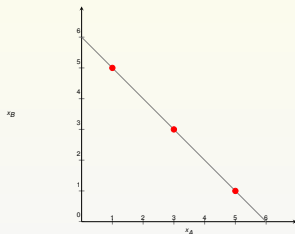
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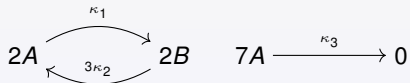
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If $R_{y \rightarrow y'}(t)$ is the number of times reaction $y \rightarrow y'$ fires by time t , then simple bookkeeping:

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$R_{y \rightarrow y'}(t)$ is a counting process with (think exponential clocks)

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Note that if Y is a unit-rate Poisson process then

$$P\left(Y\left(\int_0^{t+\Delta} \lambda_{y \rightarrow y'}(X(s))ds\right) - Y\left(\int_0^t \lambda_{y \rightarrow y'}(X(s))ds\right) = 1\right) \approx \lambda_{y \rightarrow y'}(X(t))\Delta.$$

- This suggests that the process can be represented as the solution to

$$X(t) = X(0) + \sum_{y \rightarrow y' \in \mathcal{R}} Y_{y \rightarrow y'} \underbrace{\left(\int_0^t \lambda_{y \rightarrow y'}(X(s)) ds \right)}_{R_{y \rightarrow y'}(t)} \cdot (y' - y),$$

where the $\{Y_{y \rightarrow y'}\}$ are independent unit rate Poisson processes.

- Called the random time change representation and is due to Thomas Kurtz.
- Very useful for purposes of both analysis and simulation.

Example

$$B \xrightarrow{1/3} 2B,$$

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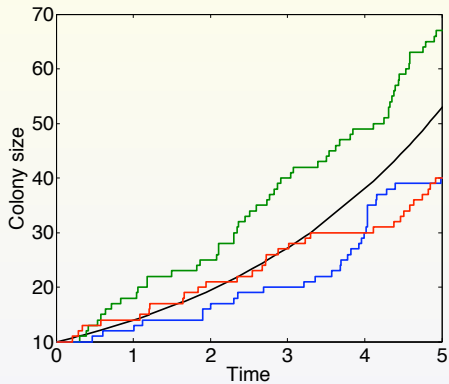
ODE:

$$\dot{x}(t) = \frac{1}{3}x(t)$$

Stochastic equation:

$$X(t) = 10 + Y \left(\int_0^t \frac{1}{3} X(s) ds \right).$$

Example: population growth



Connections between the models: LLN

Consider a parameterized family of models satisfying the following

- $X_i^V(0) = O(V)$, and
- For $y \rightarrow y' \in \mathcal{R}$,

$$\kappa_{y \rightarrow y'}^V = \frac{1}{V^{\|y\|_1 - 1}} \kappa_{y \rightarrow y'},$$

where $\|y\|_1 = y_1 + \dots + y_d$.

Example:

$$\emptyset \xrightarrow{V^{\kappa_{y \rightarrow y'}}} \mathbb{C}_{\text{complex}}$$

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Consider $Vx \in \mathbb{Z}_{\geq 0}^d$ and note that in each case,

$$\lambda_k^V(Vx) = \kappa_{y \rightarrow y'}^V \frac{Vx!}{(Vx - y)!} \approx V \kappa_{y \rightarrow y'} x^y.$$

Example: $A + B \rightarrow \dots$

$$\kappa_{y \rightarrow y'}^V \frac{Vx!}{(Vx - y)!} = V^{-1} \kappa_{y \rightarrow y'}(Vx_A)(Vx_B) = V \kappa_{y \rightarrow y'} x_A x_B.$$

Connections between the models: LLN

Now define

$$\bar{X}^V = V^{-1}X^V,$$

to be normalized process and note

$$\bar{X}^V(t) = \frac{1}{V}X_0 + \sum_{y \rightarrow y'} \frac{1}{V}Y_{y \rightarrow y'} \left(\int_0^t \lambda_{y \rightarrow y'}^V(X^V(s)) ds \right) (y' - y)$$

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Apply the Law of Large Numbers:

$$\frac{1}{V} Y_{y \rightarrow y'}(Vu) \approx u,$$

to get the usual ODE (integral version).

$$x(t) = x(0) + \sum_{y \rightarrow y'} \int_0^t \kappa_{y \rightarrow y'} x(s)^y ds \cdot (y' - y).$$

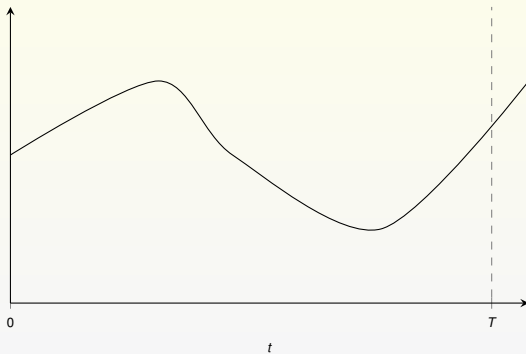
Theorem

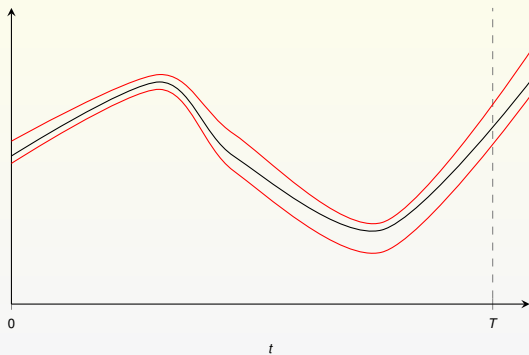
Assume that for a fixed positive state $z_0 \in \mathbb{R}_{>0}^d$ and for all $\varepsilon > 0$ we have

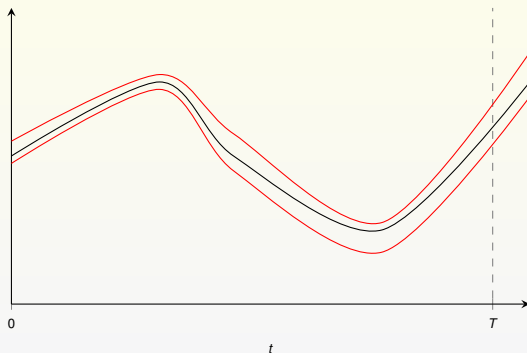
$$\lim_{V \rightarrow \infty} P\left(\left|V^{-1}X^V(0) - z_0\right| > \varepsilon\right) = 0.$$

Moreover, assume that the solution z of the ODE with $z(0) = z_0$ is unique and is defined up to a finite fixed time $T > 0$. Then, for any $\varepsilon > 0$

$$\lim_{V \rightarrow \infty} P\left(\sup_{t \in [0, T]} \left|V^{-1}X^V(t) - z(t)\right| > \varepsilon\right) = 0.$$







The probability that, up to time T , $V^{-1}X^V(t)$ is between the two red lines tends to one for $V \rightarrow \infty$.

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- No species is consumed at a higher order than its abundance (single time scale)

Multiscale Setting (single time scale)

Consider a collection of stochastic reaction networks X^V and assume there exist two non-negative vectors α, β such that:

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- No species is consumed at a higher order than its abundance (single time scale)

Theorem (Ball, Kurtz, Popovich and Rempala 2006, Pfaffelhuber and Popovich 2013, Kang and Kurtz 2013)

$$V^{-\alpha} X_t^V \xrightarrow{V \rightarrow \infty} Z_0 + \sum_{y \rightarrow y' \in \mathbb{R}_1} \hat{\xi}_{y \rightarrow y'} \int_0^t \lambda_{y \rightarrow y' \in \mathbb{R}_2}(Z_s) ds + \sum_{y \rightarrow y'} \hat{\xi}_{y \rightarrow y'} Y_{r'} \left(\int_0^t \lambda_{r'}(Z_s) ds \right)$$

up to a fixed finite time T .

Section 2

Probability measures moving!

Instead of tracking the exact **state** we are in, we can just be happy to describe the probability measures of the random variable X_t , for all t .

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It turns out, that's just a **linear ODE**! It is called the Kolmogorov Forward equation, or the chemical master equation in this context:

$$\frac{d}{dt}p(x, t) = \sum_{y \rightarrow y'} p(x - y' + y, t) \lambda_{y \rightarrow y'}(x - y' + y) - \sum_{y \rightarrow y'} p(x, t) \lambda_{y \rightarrow y'}(x),$$

where $p(x, t) = P(X(t) = x)$.

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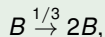
Solving this equation analytically is often difficult (impossible). Of course, if finite state space,

$$\dot{P}_t = P_t Q \implies P_t = e^{tQ}.$$

Example

$$B \xrightarrow{1/3} 2B,$$

Example



Forward equation (master equation): For $x \in \{10, 11, \dots\}$

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i.e.

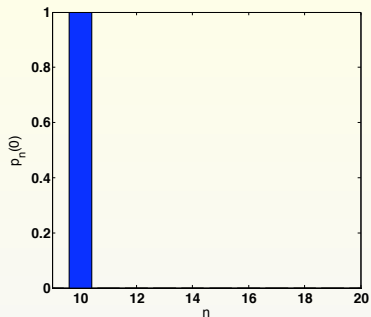
$$\frac{d}{dt}p(10, t) = \frac{1}{3} \cdot 9 \cdot p(9, t) - \frac{1}{3} \cdot 10 \cdot p(10, t)$$

$$\frac{d}{dt}p(11, t) = \frac{1}{3} \cdot 10 \cdot p(10, t) - \frac{1}{3} \cdot 11 \cdot p(11, t)$$

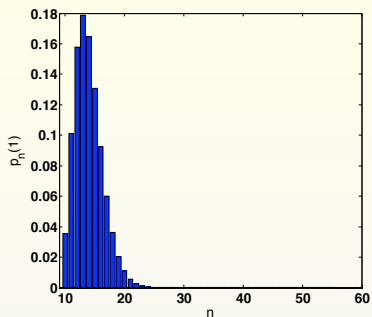
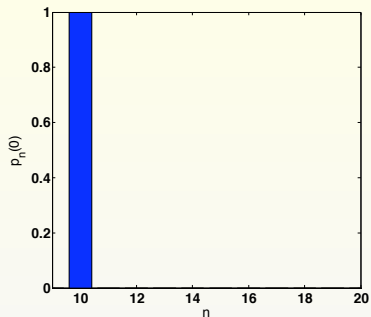
$$\frac{d}{dt}p(12, t) = \frac{1}{3} \cdot 11 \cdot p(11, t) - \frac{1}{3} \cdot 12 \cdot p(12, t)$$

⋮

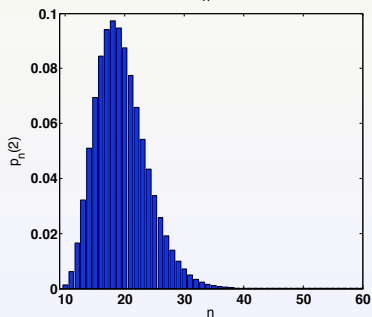
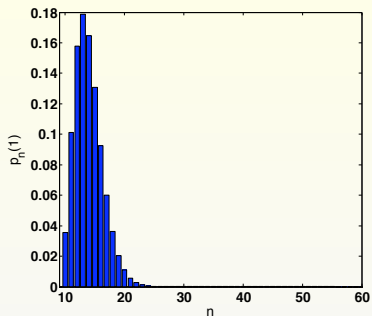
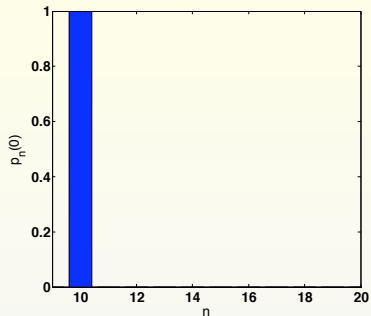
Example: population growth - evolution of distribution



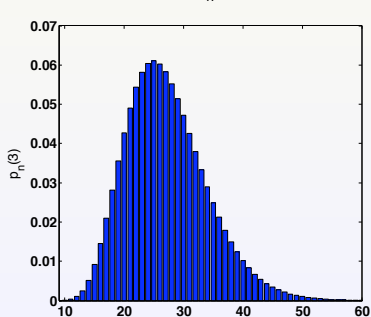
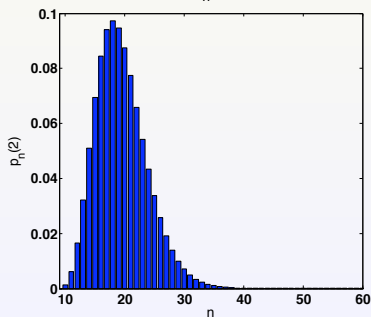
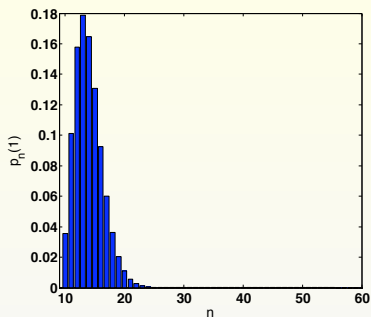
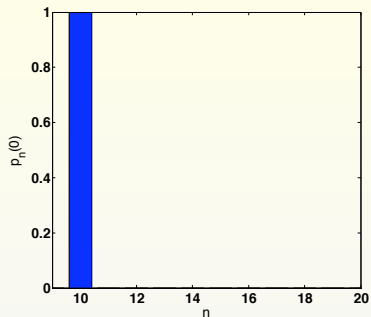
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Section 3

The notion of equilibrium in the stochastic setting

Let $p(x, t) = P(X_t = x)$.

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$$\begin{cases} p(x, 0) = P(X_0 = x) \\ \frac{dp(x, t)}{dt} = \sum_{y \rightarrow y' \in \mathbb{R}} p(x - y' + y, t) \lambda_{y \rightarrow y'}(x - y' + y) - p(x, t) \sum_{y \rightarrow y' \in \mathbb{R}} \lambda_{y \rightarrow y'}(x) \end{cases}$$

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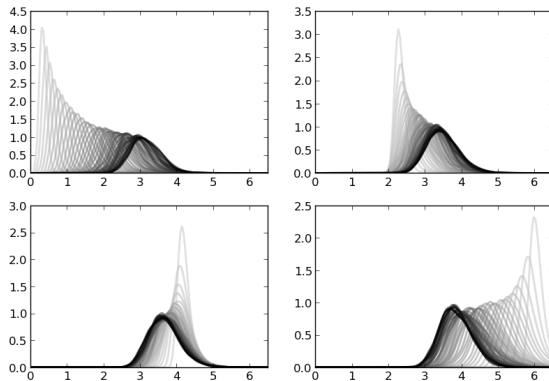
The probabilities $\pi(x)$ that are equilibrium points for the above ODE, that is such that

$$\sum_{y \rightarrow y' \in \mathbb{R}} \pi(x - y' + y) \lambda_{y \rightarrow y'}(x - y' + y) - \pi(x) \sum_{y \rightarrow y' \in \mathbb{R}} \lambda_{y \rightarrow y'}(x) = 0 \quad \forall x \in \mathbb{N}^{|\mathcal{S}|},$$

are the **stationary distributions** of the system.

Stationary distributions

Stochastic: convergence of distribution to equilibria



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$$P(X_t = x) = \pi(x).$$

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with $\pi(x)$ stationary.

- The stationary distribution are concentrated on the irreducible components.
- If we restrict X_t to an irreducible component, then the stationary distribution, if it exists, is unique.

If a SRN has a stationary distribution π , then (if the model is restricted to an irreducible component)

- for any state x

$$P(X_t = x) \xrightarrow[t \rightarrow \infty]{} \pi(x);$$

- for any state x

$$\frac{N_x(t)}{t} \xrightarrow[t \rightarrow \infty]{} \pi(x),$$

where $N_x(t)$ is the time spent by the process in state x up to time t ;

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We can use stationary distributions to

- know what is the long-term behaviour of a system;
- know what is the average expression of some protein over a long time;
- approximate multi-scale models by assuming that the faster systems are always at stationary regime;

Theorem (A, Craciun, Kurtz, 2010)

Let $\{S, C, \mathcal{R}\}$ be a chemical reaction network with rate constants κ_k . Suppose:

- 1 the network is *weakly reversible*, and
- 2 has a *deficiency of zero*.

Then, for any irreducible set Γ , the stochastic system has a product form stationary distribution

$$\pi(x) = \frac{1}{Z^V} \prod_{i=1}^d e^{-c_i} \frac{c_i^{x_i}}{x_i!}, \quad x \in \Gamma, \quad (1)$$

where Z^V is a normalizing constant and c is a *complexed-balanced equilibrium* of the corresponding ODE.

Theorem (A, Craciun, Kurtz, 2010)

Let $\{S, C, R\}$ be a chemical reaction network with rate constants κ_k . Suppose:

- 1 the network is *weakly reversible*, and
- 2 has a *deficiency of zero*.

Then, for any irreducible set Γ , the stochastic system has a product form stationary distribution

$$\pi(x) = \frac{1}{Z^V} \prod_{i=1}^d e^{-c_i} \frac{c_i^{x_i}}{x_i!}, \quad x \in \Gamma, \quad (1)$$

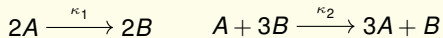
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Converse proved by Carsten Wiuf and me.

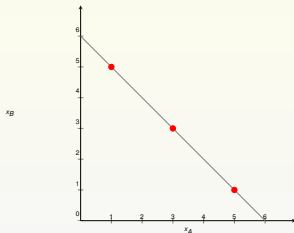
Theorem

If the stationary distribution on enough states is the distribution above, then the ODE model is complex-balanced with complex-balanced equilibrium c .

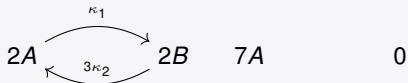
Consider



on



The dynamics are the same of



- Anderson, Craciun, Kurtz, Product-form stationary distributions for deficiency zero chemical reaction networks, 2010;
- Anderson, C., Koyama, Kurtz, Non-explosivity of stochastically modeled reaction networks that are complex balanced, 2017;
- C., Wiuf, Product-form Poisson-like distributions and complex balanced reaction systems, 2015;
- Hoessly, Mazza, Stationary distributions and condensation in autocatalytic reaction networks, 2019;
- Bibbona, Kim, Wiuf Stationary distributions of systems with discreteness-induced transitions, 2020;

- Hornos, Schultz, Innocentini, Wang, Walczak, Onuchic, Wolynes Self-regulating gene: an exact solution, 2005;
- Mélykúti, Hespanha, Khammash Equilibrium distributions of simple biochemical reaction systems for time-scale separation in stochastic reaction networks, 2014;
- Anderson, Craciun, Gopalkrishnan, Wiuf Lyapunov functions, stationary distributions, and non-equilibrium potential for reaction networks, 2015;
- Anderson, Cotter Product-form stationary distributions for deficiency zero networks with non-mass action kinetics, 2016;
- Hong, Kim, Al-Radhawi, Sontag, Kim Derivation of stationary distributions of biochemical reaction networks via structure transformation, 2021;

There are techniques to approximate the stationary distributions! As an example, state space truncation techniques ¹

¹Gupta, Mikelson, Khammash, [A finite state projection algorithm for the stationary solution of the chemical master equation](#), 2017; Kuntz, Thomas, Stan, Barahona, [Stationary distributions of continuous-time Markov chains: a review of theory and truncation-based approximations](#), 2021]

There are techniques to approximate the stationary distributions! As an example, state space truncation techniques ¹

They assume a stationary distribution exists!

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Some works connect graphical properties with existence of stationary distributions:

- Gupta, Briat, Khammash, A Scalable Computational Framework for Establishing Long-Term Behavior of Stochastic Reaction Networks, 2013;
- Anderson, Kim Some network conditions for positive recurrence of stochastically modeled reaction networks, 2018;
- Anderson, C., Kim, Stochastically modeled weakly reversible reaction networks with a single linkage class, 2020;
- Anderson, C., Kim, Nguyen Tier structure of strongly endotactic reaction networks, 2020;
- Xu, Hansen, Wiuf, Full classification of dynamics for one-dimensional continuous time Markov chains with polynomial transition rates, pre-print;
- C., Pal Majumder, Wiuf, The dynamics of stochastic mono-molecular reaction systems in stochastic environments, 2021.

Conjecture

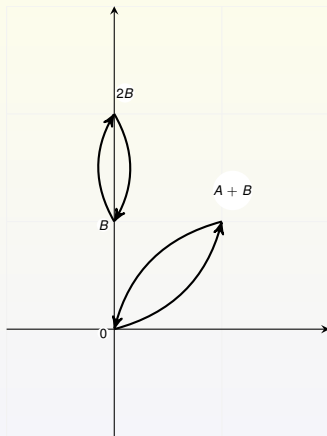
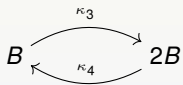
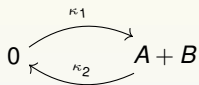
*If a network is weakly reversible, the associated stochastic mass-action system has a stationary distribution for **any choice of rate constants**.*

Conjecture

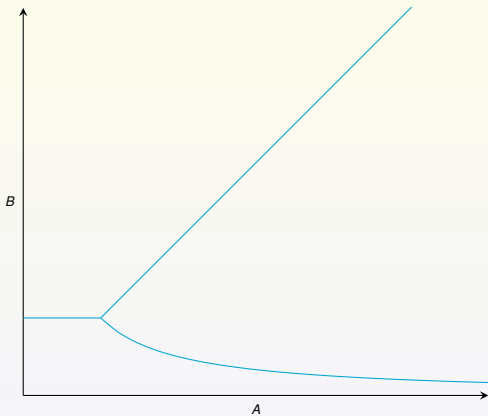
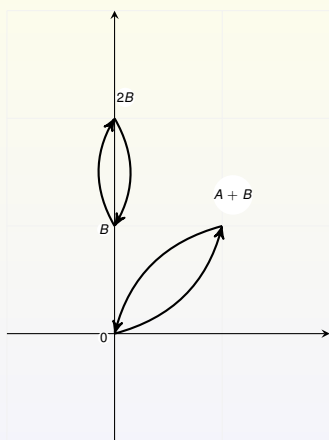
*If a network is weakly reversible, the associated stochastic mass-action system has a stationary distribution for **any choice of rate constants**.*

To prove the conjecture, we only need to prove there is no drift towards infinity.

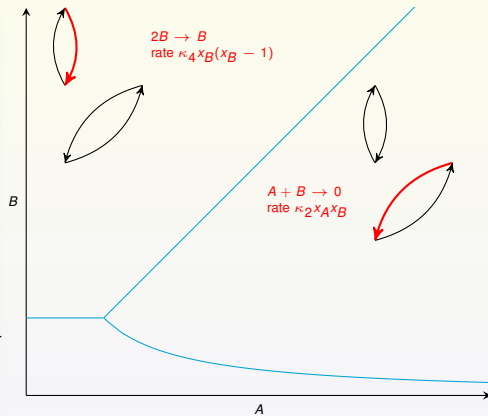
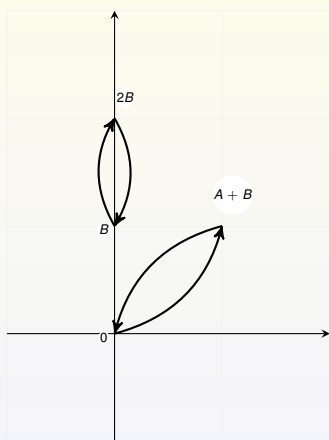
The idea



The idea



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Section 4

Foster-Lyapunov criteria

Given a function V , the generator of the process X applied to the function V is a function defined by

$$\mathcal{L}V(x) = \lim_{h \rightarrow 0} \frac{E[V(X_h) | X_0 = x] - V(x)}{h}$$

Given a function V , the generator of the process X applied to the function V is a function defined by

$$\mathcal{L}V(x) = \lim_{h \rightarrow 0} \frac{E[V(X_h) | X_0 = x] - V(x)}{h} = \frac{d}{dt} E[V(X_t)](x)$$

Consider a stochastic mass-action system $\{X(t) : t \geq 0\}$.

Theorem (Meyn and Tweedie, Stability of Markovian Processes III : Foster-Lyapunov Criteria for Continuous-Time Processes, 1993)

If there exists a scalar function V such that

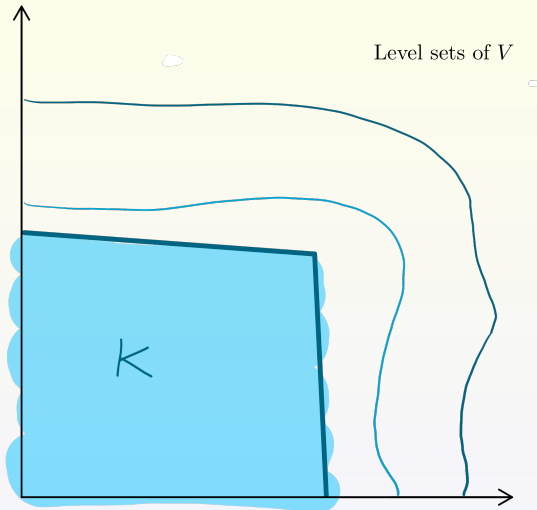
- $V(x) > 0$ for all x ;
- $\lim_{x \rightarrow \infty} V(x) = \infty$;
- *there exists a compact set K and $c > 0$ such that*

$$\mathcal{L}V(x) = \sum_{y \rightarrow y'} \lambda_{y \rightarrow y'}(x) \left(V(x + y' - y) - V(x) \right) < -c$$

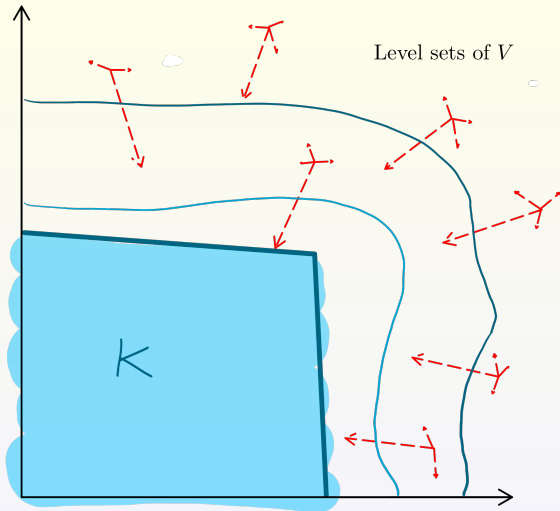
for all $x \notin K$.

Then, X has a stationary distribution.

Foster-Lyapunov criterium



Foster-Lyapunov criterium



In order to have

$$\mathcal{L}V(x) = \sum_{y \rightarrow y'} \lambda_{y \rightarrow y'}(x) \left(V(x + y' - y) - V(x) \right) < -c \quad (2)$$

we can try to construct a function V that **decreases along the most likely transitions**, given by the **dominant reactions**.

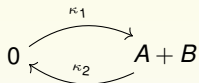
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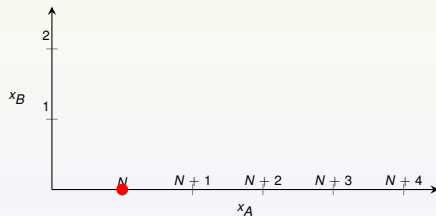
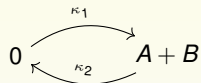
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This strategy is used, for example, in Anderson, Kim Some network conditions for positive recurrence of stochastically modeled reaction networks, 2018; Anderson, C., Kim, Stochastically modeled weakly reversible reaction networks with a single linkage class, 2020; Anderson, C., Kim, Nguyen Tier structure of strongly endotactic reaction networks, 2020.

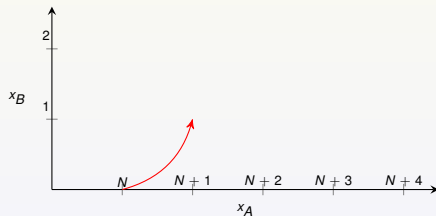
The boundary is often a problem



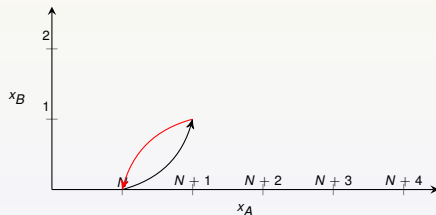
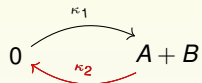
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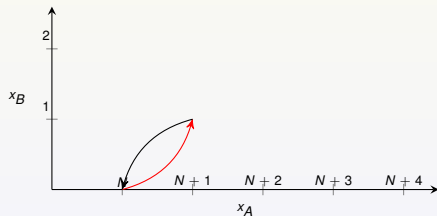
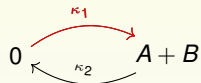
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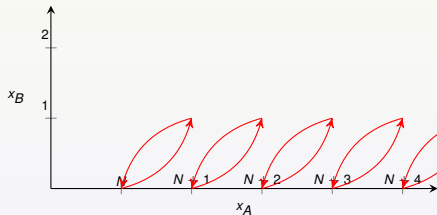
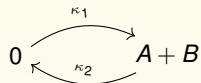
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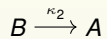
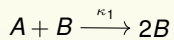
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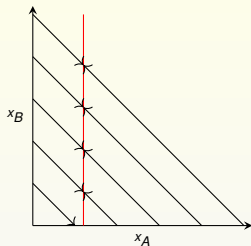
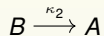
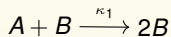
Section 5

Discrepancies between the long-term behaviour of deterministic
and stochastic models

Consider the mass-action system



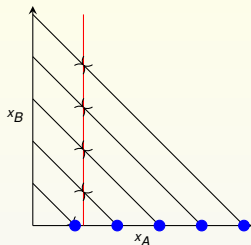
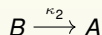
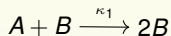
Consider the mass-action system



- In the deterministic setting, if $z_A(0) + z_B(0) = N$ with $N > \frac{\kappa_2}{\kappa_1}$, then

$$\lim_{t \rightarrow \infty} z(t) = \left(\frac{\kappa_2}{\kappa_1}, N - \frac{\kappa_2}{\kappa_1} \right).$$

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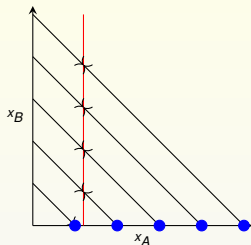
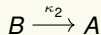
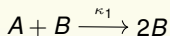


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- In the stochastic setting, the extinction of the species B will eventually occur, and almost surely $\lim_{t \rightarrow \infty} X(t) = (N, 0)$

Consider the mass-action system

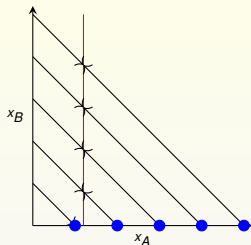
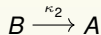
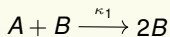


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Also: the deterministic model does not give the mean values of the stochastic process!

Section 6

Boundary Equilibria and Absorption

Idea! Since there is a boundary steady state, and the stochastic model explores around, it will be found!

²David F. Anderson, Daniele Cappelletti, *Discrepancies between extinction events and boundary equilibria in reaction networks*

Idea! Since there is a boundary steady state, and the stochastic model explores around, it will be found!

However we proved by example² that

Lack of positive equilibria



Extinction

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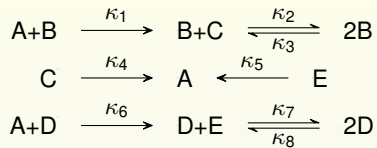
Extinction

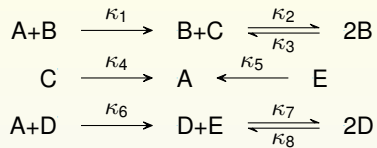
Existence of stationary distribution
on every state

⇒

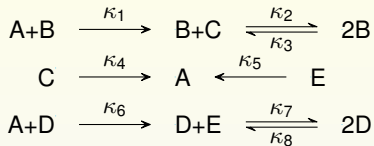
Positive equilibria

²David F. Anderson, Daniele Cappelletti, *Discrepancies between extinction events and boundary equilibria in reaction networks*



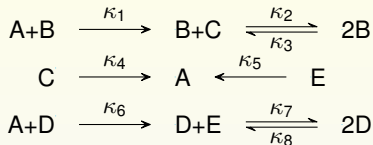


- $A + B + C + D + E$ is conserved;



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- There is no positive equilibrium unless

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$$\frac{\kappa_3 \kappa_4}{\kappa_1 \kappa_2} = \frac{\kappa_5 \kappa_8}{\kappa_6 \kappa_7}.$$

- There is a stationary distribution with mass on all states: The sets $\{B = 0\}$ and $\{D = 0\}$ are absorbing, but cannot be reached.

Section 7

Strongly Endotactic Networks

Definition

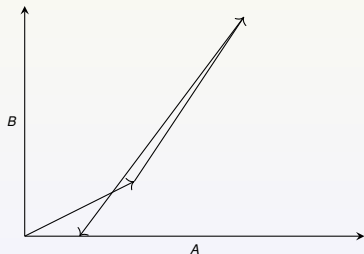
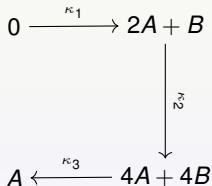
Let H be the convex hull formed by the source complexes. A network is called strongly endotactic if

- all the reactions point inside or along the faces of H ;
- for each face of H there is at least one reaction originated in the face and pointing away from it.

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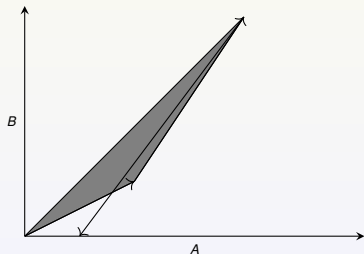
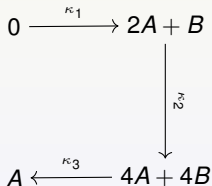


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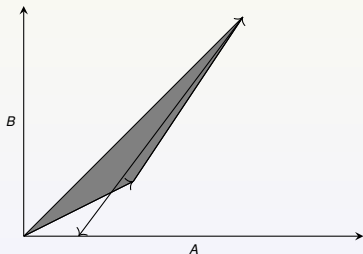
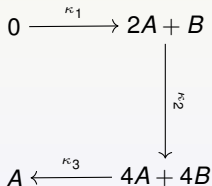


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The network is strongly endotactic!

Theorem (Gopalkrishnan, Miller, and Shiu, SIAM J. Appl. Dyn. Syst., 2014)

Consider a deterministic mass-action system which is strongly endotactic. Then, there exists a compact global attractor within each stoichiometric compatibility class, for any choice of rate constants (permanence).

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If a network is strongly endotactic and no subset of the state space boundary is absorbing, then the rescaled stochastic mass-action system satisfies a sample path Large Deviation Principle in the supremum norm.

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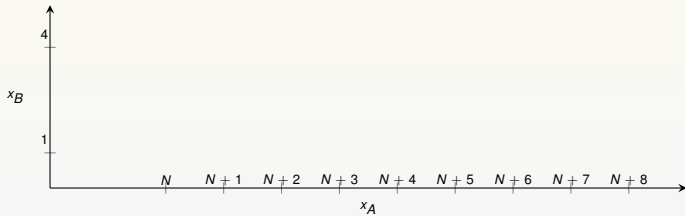
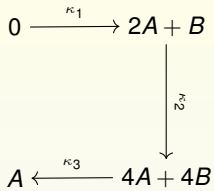
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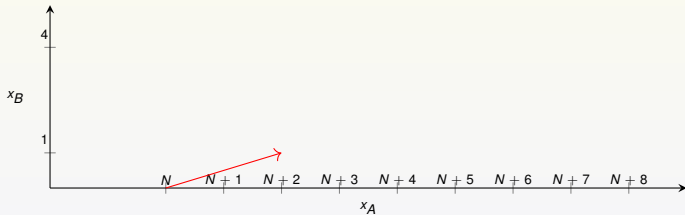
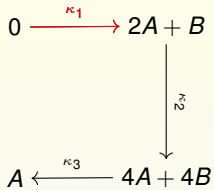
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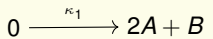
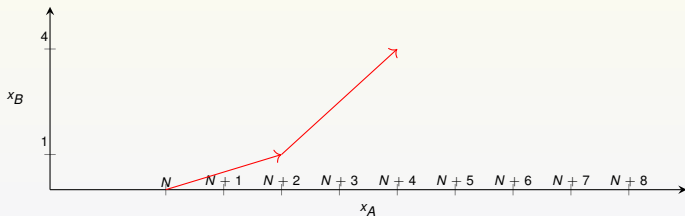
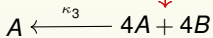
When stochastically modeled, the network of the previous example is transient!

$$\begin{array}{ccc} 0 & \xrightarrow{\kappa_1} & 2A + B \\ & & \downarrow \kappa_2 \\ A & \xleftarrow{\kappa_3} & 4A + 4B \end{array}$$

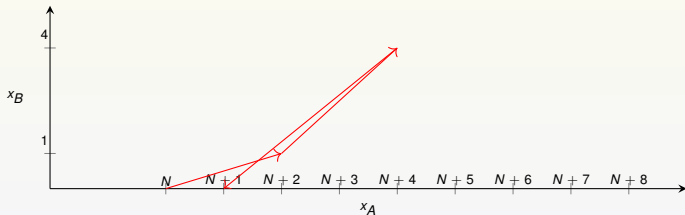
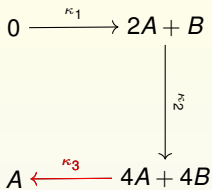




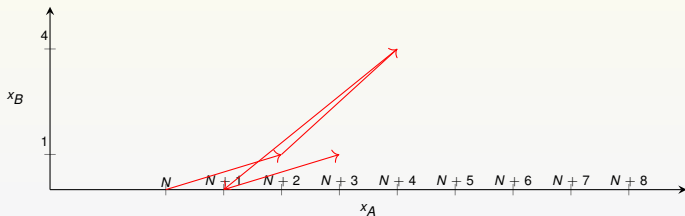
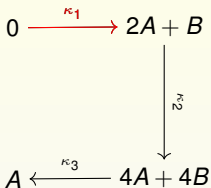
Probability ≈ 1 .


 κ_2


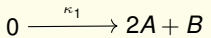
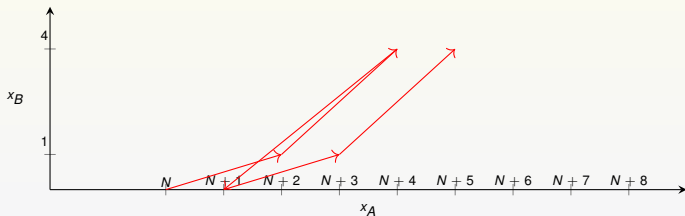
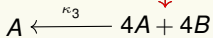
$$\text{Probability} \approx 1 \cdot \frac{\kappa_2(N+2)^2}{\kappa_2(N+2)^2 + \kappa_1}$$



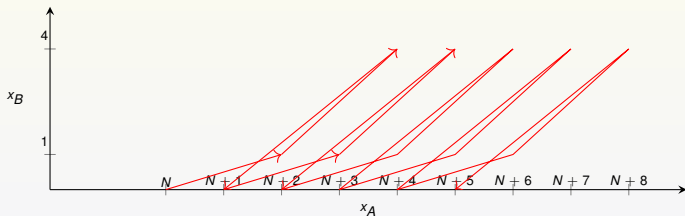
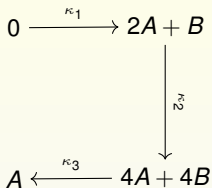
$$\text{Probability} \approx 1 \cdot \frac{\kappa_2(N+2)^2}{\kappa_2(N+2)^2 + \kappa_1} \cdot \frac{\kappa_3(N+4)^4}{\kappa_3(N+4)^4 + \kappa_2(N+4)^2 + \kappa_1}$$



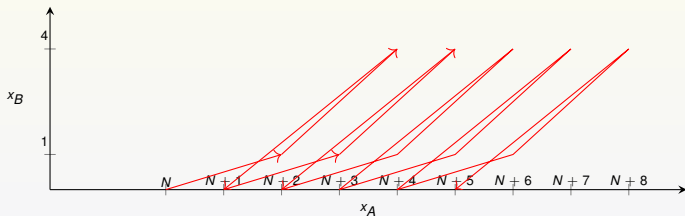
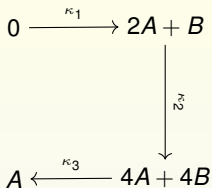
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 $\downarrow \kappa_2$


$$\text{Probability} \approx 1 \cdot \frac{\kappa_2(N+2)^2}{\kappa_2(N+2)^2 + \kappa_1} \cdot \frac{\kappa_3(N+4)^4}{\kappa_3(N+4)^4 + \kappa_2(N+4)^2 + \kappa_1} \cdot 1 \cdot \frac{\kappa_2(N+3)^2}{\kappa_2(N+3)^2 + \kappa_1} \dots$$



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Theorem (Anderson, C., Kim and Tung, SPA 2020)

If a network is strongly endotactic, then it is positive recurrent after adding outflows and inflows for every species, that is reactions of the type $mS \rightarrow 0$ and $0 \rightarrow m'S$, for specific choices of m (it should be bigger than the maximum stoichiometricity minus 1).

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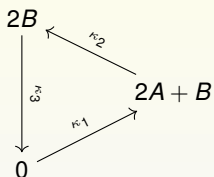
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If a bimolecular network is strongly endotactic, then it is positive recurrent after adding reactions of the type $S \rightarrow 0$ and $0 \rightarrow S$ for all species.

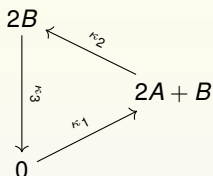
When is it true that the union of two positive recurrent networks is positive recurrent?

The stochastic mass-action system

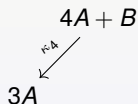


is complex balanced (hence positive recurrent) for any choice of rate constants.

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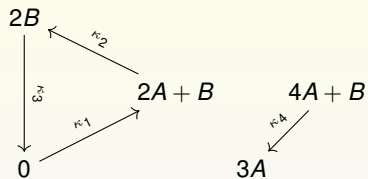


is complex balanced (hence positive recurrent) for any choice of rate constants. If we add the reaction

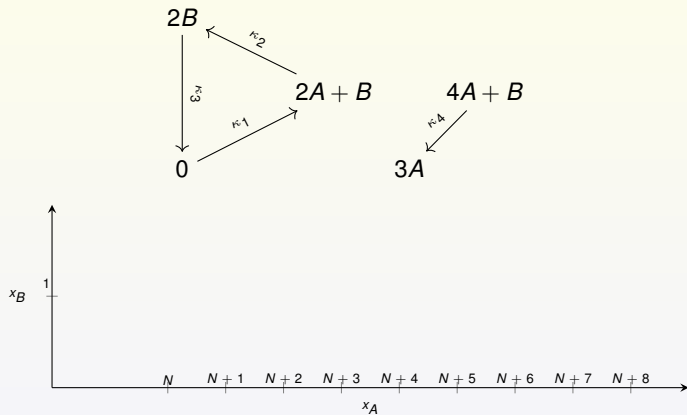


which may seem innocent enough (it consumes both A and B), the model becomes transient (for any choice of rate constants).

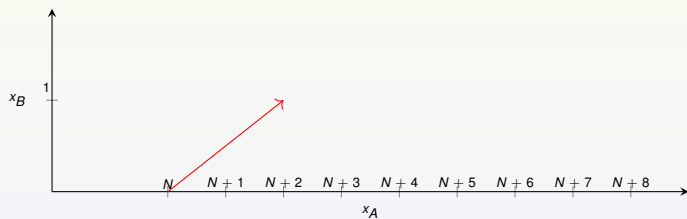
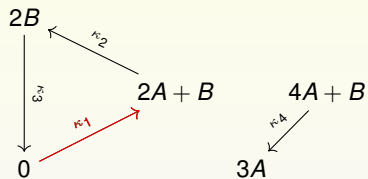
Union of networks, a warning



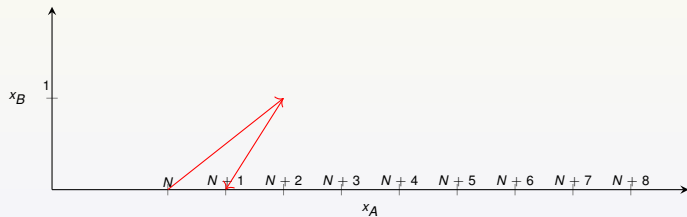
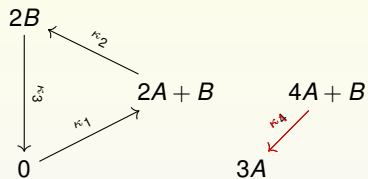
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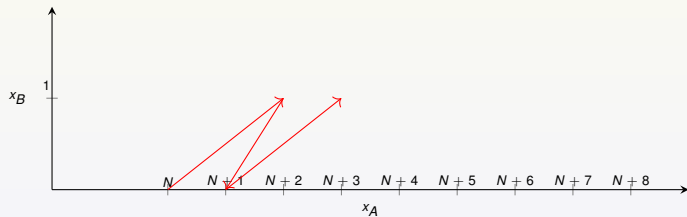
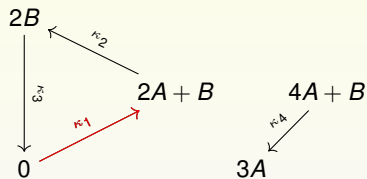
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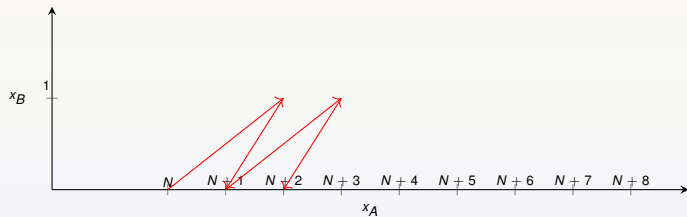
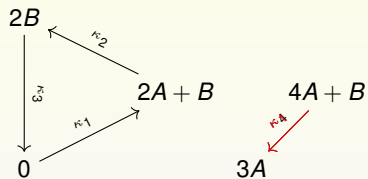
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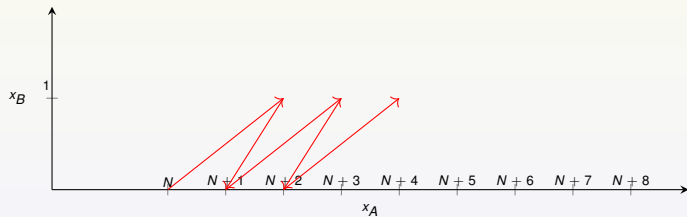
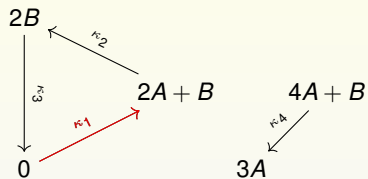
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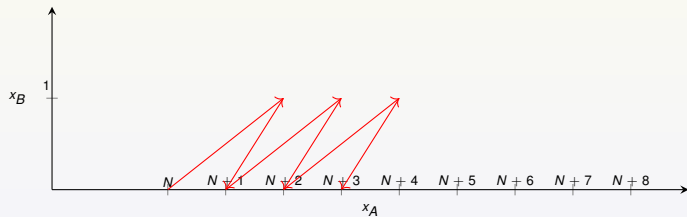
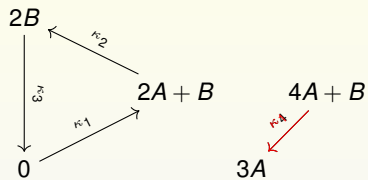
Union of networks, a warning



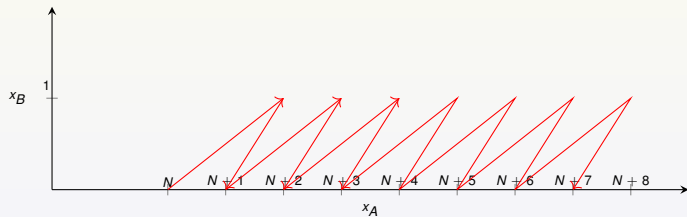
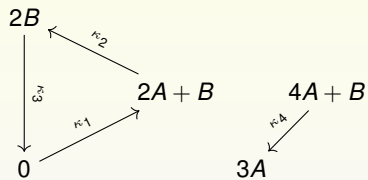
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Theorem (M. Feinberg and G. Shinar, Science, 2010)

Consider a deterministic mass-action system that

- has a *deficiency of one*.
- *admits a positive steady state* and
- has two non-terminal complexes that *differ only in one species S* ,

then the system has *absolute concentration robustness in S* .

Examples:

1

$A, \quad A + B$

differ in species B .

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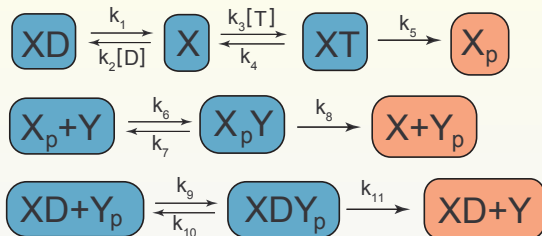
differ in species Y_p .

3

$$G, \quad 2G$$

differ in species G .

Terminal and non-terminal complexes



- The orange complexes are called **terminal**.
- The blue complexes are called **non-terminal**.

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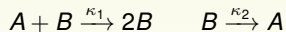
^aDavid F. Anderson, Germán Enciso, and Matthew Johnston, *Stochastic analysis of biochemical reaction networks with absolute concentration robustness*, J. Royal Society Interface, Vol. 11, 2014.

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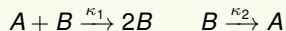
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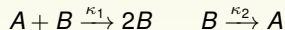
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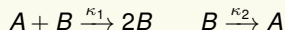
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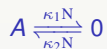
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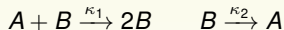


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If N is big:

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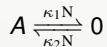


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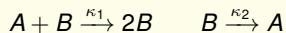


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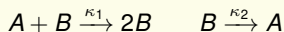
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The above reaction system has Poisson stationary distribution!

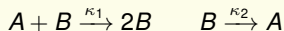


²David F. Anderson, Daniele Cappelletti, and Thomas G. Kurtz, *Finite time distributions of stochastically modeled chemical systems with absolute concentration robustness*, SIAM Journal on Applied Dynamical Systems 2017, vol. 16(3)



$$\sup_N X_A^N(0) < \infty \text{ and } N^{-1} X_B^N(0) \xrightarrow{N \rightarrow \infty} 1$$

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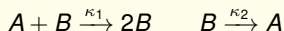
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Theorem (Anderson, C. and Kurtz, 2017)

For any fixed time points $T > \delta > 0$ and any continuous bounded φ ,

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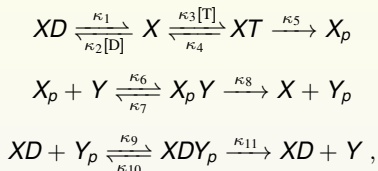
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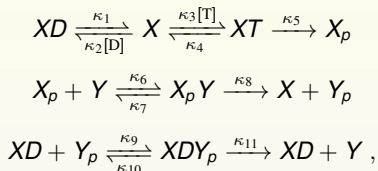
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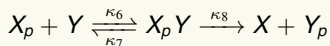
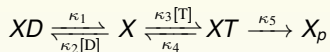
modelling EnvZ/OmpR osmoregulatory signaling system in *Escherichia coli*.

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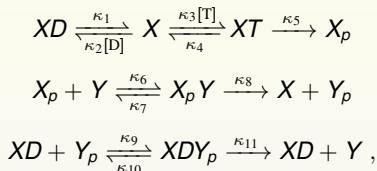
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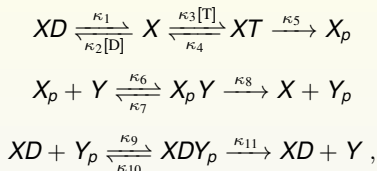
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Theorems: deterministic and stochastic

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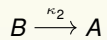
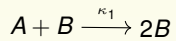
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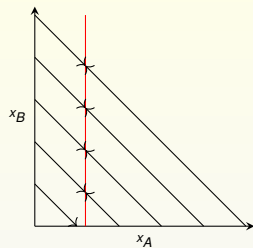
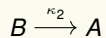
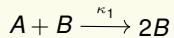
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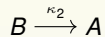
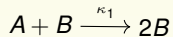
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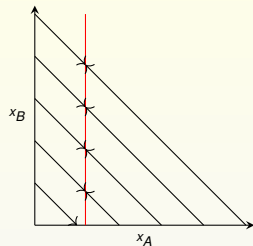


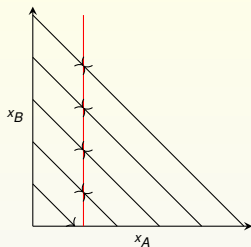
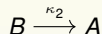
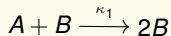


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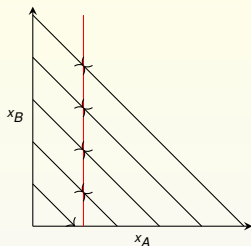
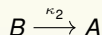
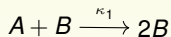


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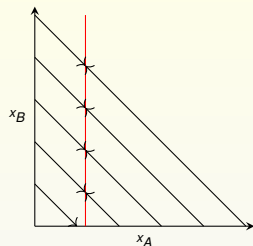
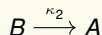
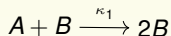




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Conjecture

Consider a stochastic mass-action system that is ACR, if deterministically modeled. Then, with probability one it undergoes an extinction.

Theorem (Anderson, Enciso, Johnston, 2014)

Consider a stochastic mass-action system that:

- has a *deficiency of one*.
- *admits a positive steady state* and
- has two non-terminal complexes that *differ only in species S* ,
- (*new*) is conservative,

then with probability one the system undergoes an extinction.

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the conclusions do not hold anymore.

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Hence ACR (+ bimolecularity, mass conservation etc.) does not imply extinction.

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